2017-01-06 Exam problems, Architecture

- 1. Plane Cartesian (*Oxy*) and polar ($O_{\rho}\theta$) coordinate systems; relations $x = \rho \cdot \cos\theta$, $x = \rho \cdot \sin\theta$.
- 2. Equations of plain curves given explicitly (e.g., $y = \operatorname{atan} x$; $\rho = \exp\theta a$ Bernoulli/logarithmic spiral), implicitly (e.g., $x^2/a^2 + y^2/b^2 = 1 - an$ ellipse) and parametrically (e.g. $x = a \cdot (t - \sin t)$, $y = a \cdot (1 - \cos t) - a$ cycloid; $x = a \cdot (2\cos t - \cos 2t)$, $y = a \cdot (2\sin t - \sin 2t - a \text{ cardioid})$.
- 3. Plane vectors: the point, Euclid(ean) and Descartes/Cartesian definitions: (*P*, *Q*), (*P*, *m*, *k*, s), $(x_P, y_P; x_Q, y_Q)$. A free vector (and the equivalency relation in the set of all plane vectors).
- 4. *n*-dimensional vectors.
- 5. Dot/inner/scalar product of vectors: $u \cdot v$, or $\langle u, v \rangle$, on the plane, in the space R3, in a space Rⁿ.
- 6. Cross product of vectors: $u \times v$ (geometrical definition, analytical formula).
- 7. Equations of a line on the real plane (i.e., in the space R^2) and in R^3 .
- 8. Equations of a plane (in *R*³).
- 9. Matrices, their types (e.g., a square matrix, an upper triangular matrix, an invertible/non-singular matrix) and their algebra (the equality, the sum, the difference, the Cauchy product).
- 10. Determinant of the matrix its definition, Laplace expansion, properties.
- 11. Sale (a system of algebraic linear equations), its solvability (Kronecker-Capelli theorem) and methods to solve them (via Cramer's rules, via inverse matrix, via Gauss elimination method).
- 12. Polynomial collocation problem the Vandermonde technique, the Lagrange polynomial.
- 13. Polynomial least-square approximation/fit.
- 14. Number/numerical sequences (with examples, also that defined recursively, e.g. Fibonacci sequence), their types (a.o., monotone, increasing, bounded, divergent, convergent; with examples, e.g., arithmetic sequence, geometric sequence, 0-1 sequence). The necessary condition a sequence (a_n) to be convergent (a_{n+1}-a_n → 0 as n → ∞). Algebra of sequences and of their limits (their equality, sum, difference; the sandwich theorem). The theorem on a monotone and bounded sequence.
- 15. Bernoulli (or sequential) definition of the (Euler) number *e*. Graphs $y = e^{\lambda_x}$ (with $\lambda > 0$, $\lambda = 0$ and $\lambda < 0$), $y = \cosh x a$ catenary, $y = \sinh x$.
- Number/numerical series: the definition, the convergence, the necessary condition a series Σa_k to be convergent (a_k → 0 as k → ∞), the quotient/d'Alembert and the root/Cauchy criteria of convergence, the Leibniz criterion (concerning an alternating series). Examples: harmonic (1+1/2+1/3+1/4+...=∞), Brounckner (aka alternating harmonic, 1-1/2+1/3-1/4+...=In2), Huygens (Σ1/t_k=2, where t_k is k-th triangle number), Madhava/Gregory/Leibniz (1-1/3+1/5-1/7...=π/4), Basel (1+1/2²+1/3²+1/4²+...=π²/6), Euler (1+1/2!+1/3!+1/4!+...=e).
- 17. Function sequences (e.g., $1/x^n$, $x \in (0,1)$) and series (incl. Taylor series, e.g., for 1/(1-x), expx, sinx).
- 18. Differential calculus: the definition of the derivative, its geometrical and physical interpretations. Algebra of differentiation (the derivative of a linear combination, of the product and of the quotient of functions, of the superposition, of the inverse function all items with examples).
- 19. Equation of the line which is tangent to a differentiable function.
- 20. Rolle and Lagrange theorems on a mean value in the differential calculus.
- 21. Fermat theorems on extrema and on the monotonicity.
- 22. Differential investigations on the convexity of a function.
- 23. De l'Hopital rules. Finding the direction coefficient of an asymptotic line.
- 24. AVSPAMECI (arguments, values, symmetry, periodicity, asymptotics, monotonicity and extrema, convexity and inflections) a schema to recognize the shape of a curve y = f(x).
- 25. Antiderivative and an indefinite integral definitions, geometric interpretations and examples.
- 26. Riemann integral and its geometrical interpretation. Newton-Leibniz fundamental theorem in the calculus.
- 27. The Gauss/bell curve $y = \exp(-x^2)/(2\pi)^{1/2}$ and a normal distribution.
- 28. Newton cooling problem, its description via an ordinary differential equation of the 1st order (ODE1) and its solution.
- 29. Complex numbers. Euler formula: $\exp z = e^r \cdot (\cos u + i \cdot \sin u)$, where $z = r + i \cdot u$, and $r, u \in R$.
- 30. Linear ordinary differential equation of the 2nd order (ODE2) and its solution (when its characteristic equation has two distinct real zeros, a double zero, and complex solutions).